

Implementation of advanced numerical solvers in FLAC3D thermal and fluid implicit formulation

Andrey V. Pyatigorets, David B. Russell

FLAC3D thermal and fluid logic

• FLAC3D thermal / fluid logic adopt energy-balance / fluid mass-balance equations formulated at each gridpoint:

$$\frac{dT_n}{dt} = -\frac{1}{\sum m_{th}^n} Q_{th}^n \qquad \frac{dP_n}{dt} = -\frac{1}{\sum m_{fl}^n} Q_{fl}^n$$

- FLAC3D thermal and fluid modules have two separate solvers: explicit and implicit
- Explicit solver uses forward difference scheme: $T_{new} = T_{old} + \Delta t \cdot f(T_{old})$

Timestep Δt must be small (often $10^{-4} \leftrightarrow 10^{-6}$ sec)!

- Current implicit solver uses:
 - \circ Central difference (Crank-Nicolson) scheme to obtain a system of linear equations for <u>each gridpoint</u>: $A_{nj}\Delta T_{j\langle t\rangle}=b_{n\langle t\rangle}$
 - Jacobi method (iterative) to solve it

Jacobi solver easily diverges (fails) when $\Delta t_{implicit} \gtrsim ~ [{f 10} \leftrightarrow {f 100}] ~ \Delta t_{explicit}$

Need to find an approach which will allow using much larger timestep in the implicit scheme!



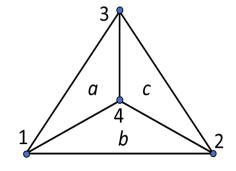
New approach – use global matrix

 Global matrix is assembled for the whole model based on previously calculated local matrices:

$$\begin{bmatrix} Q_1^a \\ Q_4^a \\ Q_3^a \end{bmatrix} = \begin{bmatrix} c_{11}^a & c_{14}^a & c_{13}^a \\ & c_{44}^a & c_{43}^a \\ & & c_{33}^a \end{bmatrix} \begin{bmatrix} \Delta T_1 \\ \Delta T_4 \\ \Delta T_3 \end{bmatrix}$$

$$\begin{bmatrix} Q_1^b \\ Q_2^b \\ Q_4^b \end{bmatrix} = \begin{bmatrix} c_{11}^b & c_{12}^b & c_{14}^b \\ & c_{22}^b & c_{24}^b \\ & & c_{44}^b \end{bmatrix} \begin{bmatrix} \Delta T_1 \\ \Delta T_2 \\ \Delta T_4 \end{bmatrix}$$

$$\begin{bmatrix} Q_2^c \\ Q_3^c \\ Q_4^c \end{bmatrix} = \begin{bmatrix} c_{22}^c & c_{23}^c & c_{24}^c \\ & c_{33}^c & c_{34}^c \\ & & c_{44}^c \end{bmatrix} \begin{bmatrix} \Delta T_2 \\ \Delta T_3 \\ \Delta T_4 \end{bmatrix}$$



$$\begin{bmatrix} Q_{1} \\ Q_{2} \\ Q_{3} \\ Q_{4} \end{bmatrix} = \begin{bmatrix} Q_{1}^{a} + Q_{1}^{b} \\ Q_{2}^{b} + Q_{2}^{c} \\ Q_{3}^{a} + Q_{3}^{c} \\ Q_{4}^{a} + Q_{4}^{b} + Q_{4}^{c} \end{bmatrix} = \begin{bmatrix} c_{11}^{a} + c_{11}^{b} & c_{12}^{b} & c_{13}^{a} & c_{14}^{a} + c_{14}^{b} \\ c_{22}^{b} + c_{22}^{c} & c_{23}^{c} & c_{24}^{b} + c_{24}^{c} \\ c_{22}^{a} + c_{22}^{c} & c_{33}^{a} + c_{33}^{c} & c_{43}^{a} + c_{34}^{c} \\ c_{44}^{a} + c_{44}^{b} + c_{44}^{c} \end{bmatrix} \begin{bmatrix} \Delta T_{1} \\ \Delta T_{2} \\ \Delta T_{3} \\ \Delta T_{4} \end{bmatrix}$$

Real global matrix is very sparse, symmetric and positive definite!



New solvers

- Two new solvers from INTEL MKL are adopted:
 - **Preconditioned Conjugate Gradient (PCG) Solver** iterative solver for very large sparse systems (e.g. millions of equations). Uses simple Jacobi (diagonal) preconditioner.
- Direct Sparse Solver (DSS) direct solver for smaller sparse systems (equivalent to matrix inversion; LU / Chlolesky).
- New solvers operate on *global matrix* representing the whole model. The matrix must be assembled in compressed sparse format (CSR3) done once when user calls new solvers.
- Global matrix must be symmetric and positive definite. To check this and to find matrix condition number κ , extremal eigenvalues are calculated (Krylov-Schur method). Limit on number if iteration in PCG:

$$\kappa = \frac{\lambda_{max}}{\lambda_{min}}, \qquad n \le \frac{1}{2} \kappa \log \frac{2}{\varepsilon}$$

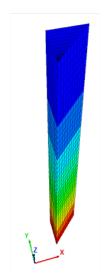
• Solvers are unconditionally stable! Solution can always be found up to the specified accuracy (providing the time step is below the characteristic time of the model)!

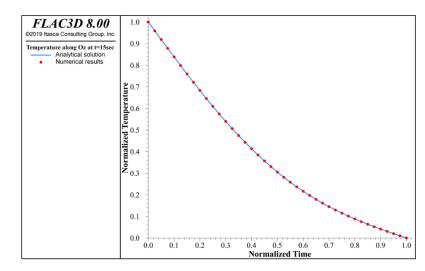


Performance

• Simple diffusion problem: $T_{bot} = 100$ C, $T_{top} = 0$.

Results of temperature distribution after 15sec:





Scheme / Solver	Explicit	Implicit / Jacobi	Implicit / precond. CG	Implicit / direct
Timestep	1.28856e-5	1e-4	0.5	0.5
Number of steps	1164094	150000	30	30
Error	2e-5	5e-4	9e-5	9e-5
Relative speed-up (runtime)	1X (11m02s)	2.1X (5m13s)	441X (1.5sec)	662X (1sec)
Time/Step	5.68e-4	2.09e-3 (3.7x)	5e-2 (88x)	3.33e-2 (58x)

Overall speed-up over the explicit logic is $10^2 - 10^6$

(for thermal diffusion problems involving large time step and large calculation time)

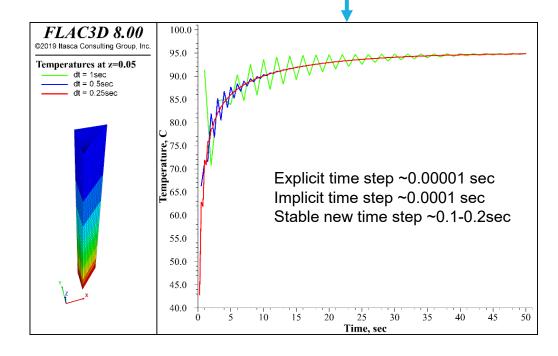
New solvers have been tested on:

- heat conduction,
- thermo-mechanical coupling,
- constant and transient boundary conditions,
- heat sources/sinks,
- convective boundaries.



Challenges / limitations

- Currently there is an issue within thermal/fluid Attach logic which does not properly account for presence of interfaces within same zone (when multiple attach conditions have to be resolved).
- Possible oscillations (from C-N scheme) for large time steps (so small number of cycles)!
- The global matrix has to be re-assembled every time the model geometry or physical properties of gp/zones change.
 Thus, new solvers may be inefficient for:
 - Problems in large strain mode
 - Problems with moving boundaries
 - Problems requiring small time step

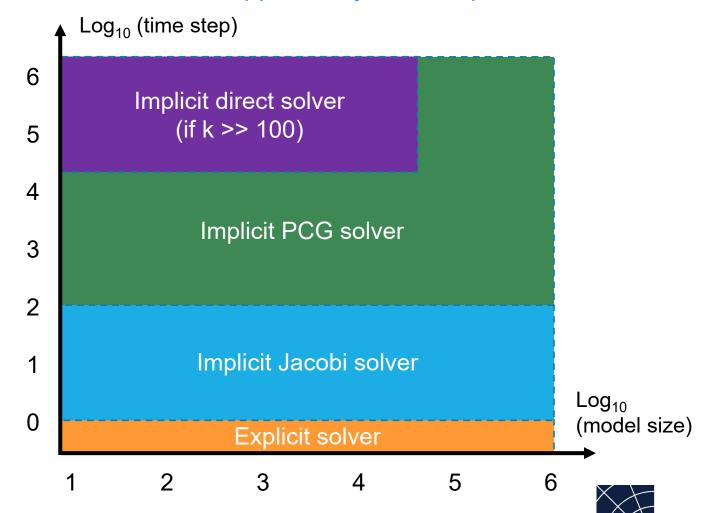




Applicability

- Choice of proper solver is done by user:
 - Explicit method
 - Implicit Jacobi solver
 - Implicit PCG solver
 - Implicit direct solver
- It depends on:
- Physical parameters (i.e. time-dependent)
- Boundary conditions (i.e. time-dependent)
- Timestep
- Model size

Generic solvers applicability for best performance



Command syntax

```
model configure thermal
```

model thermal active on

• zone thermal implicit on



FLAC3D 7: calls Jacobi solver only

FLAC3D 8: calls Jacobi solver; if diverges – automatically switches to PCG solver

- zone thermal implicit on solver-jacobi
- zone thermal implicit on solver-pcg [preserve]
- zone thermal implicit on solver-direct [preserve]

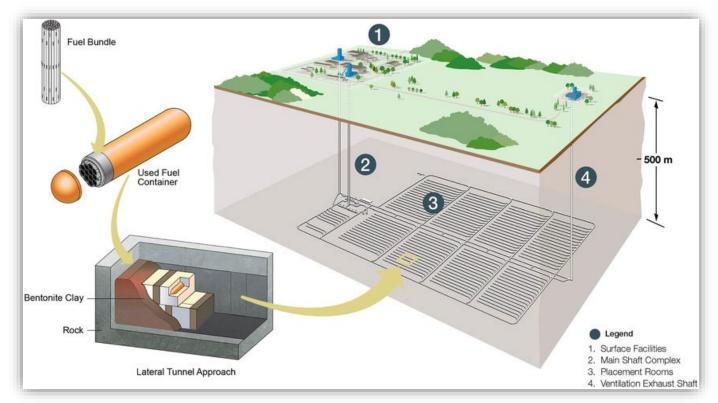
```
model thermal timestep fix ...
```

model cycle ... / solve time ...

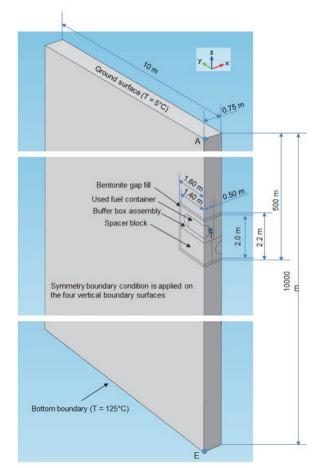


NWMO project

Long-Term Stability Analysis of APM Conceptual Repository Design in Sedimentary and Crystalline Rock Settings (2015) (NWMO-TR-2015-27)



Hall, Keech (2017). Corr. Eng., Science and Techn.



Ruiping Guo NWMO-TR-2016-03



NWMO project

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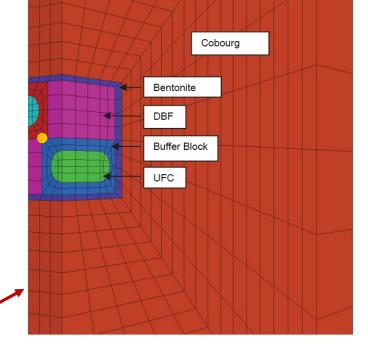
Long-Term Stability Analysis of APM Conceptual Repository Design in Sedimentary and Crystalline Rock Settings (2015) (NWMO-TR-2015-27)

Temperature simulation in a nuclear waste repository over 1 million years

- FLAC3D 5 runtime is ~ 1 month with single-thread thermal logic
- FLAC3D 7 runtime ~ 2-4 weeks with multi-threaded thermal logic
- FLAC3D 8 runtime is ~ 25-30 minutes using combination of new solvers
- The largest stable timestep for Jacobi solver (old technique) \sim 30 days

2km

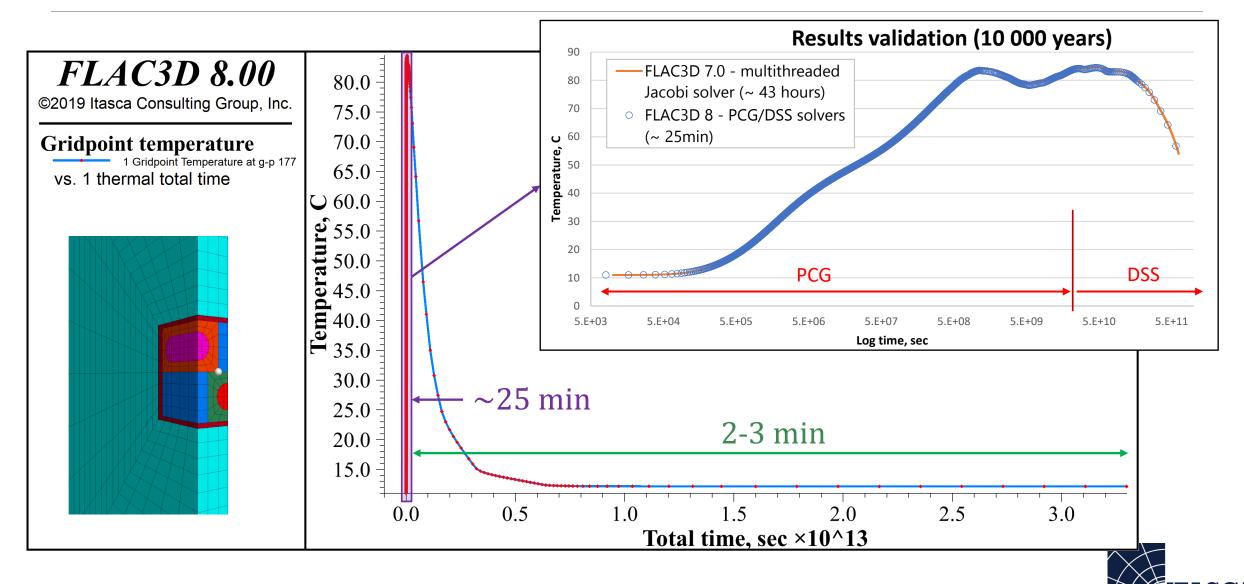
• The largest timestep used in new solvers \sim 1200 years (limited artificially, solvers allow larger)



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NWMO results



NWMO results

